

# Some control results for Stokes equations with memory

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System with nonlocal in time (memory) term:

$$\begin{cases} u_t - \Delta u - b \int_0^t e^{-a(t-s)} \Delta u(\cdot, s) ds + \nabla p = 0, \\ \nabla \cdot u = 0 \end{cases}$$

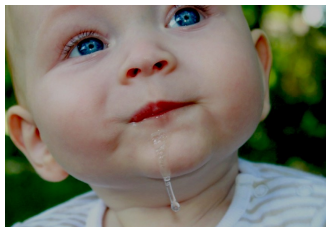


Figure: Saliva



Figure: Honey

Control systems are those whose behavior can be influenced by the action of an additional variable (the control).

$$\begin{cases} u_t = Au + Bv, \\ u(0) = u_0 \quad + \quad B.C. \end{cases}$$

where  $u : [0, T] \mapsto \mathcal{H}$  is the *state* and  $v \in \mathcal{U}$  is the *control*.

- *Exact controllability (EC) at time  $T$ :*

For any  $u_0, u_T \in \mathcal{H}$ , find  $v \in \mathcal{U}$  such that  $u(T) = u_T$ .

- *Null controllability (NC) at time  $T$ :*

For any  $u_0 \in \mathcal{H}$ , find  $v \in \mathcal{U}$  such that  $u(T) = 0$ .

- *Approximate-finite dimensional controllability (A-FD) at time  $T$ :*

For any  $u_0, u_T \in \mathcal{H}$ , any finite dimensional space  $M \subset \mathcal{H}$  and for every  $\varepsilon > 0$ , find  $v \in \mathcal{U}$  such that

$$\|u(T) - u_T\|_{\mathcal{H}} \leq \varepsilon \text{ and } P_M(u(T)) = P_M(u_T).$$

Model **nonlinear** system:

$$\left\{ \begin{array}{ll} \partial_t u - \nu \Delta u + (u \cdot \nabla)u + \nabla p = \nabla \cdot \tau + \nu \mathbf{1}_\omega & \text{in } Q, \\ \partial_t \tau + (u \cdot \nabla)\tau + g(\nabla u, \tau) + a\tau = 2bDu & \text{in } Q, \\ \nabla \cdot u = 0 & \text{on } Q, \\ u = 0 & \text{on } \Sigma, \\ u(0) = u_0, \quad \tau(0) = \tau_0 & \text{on } \Omega. \end{array} \right.$$

Here,  $(u, \tau)$  is the **state**,  $\nu$  is the **control** and

$$g(\nabla u, \tau) := \tau Wu - Wu\tau - k(Du\tau + \tau Du) \quad \text{and} \quad k \in [-1, 1].$$

- it models a non-Newtonian homogeneous fluid with memory.
- More difficult to solve than NS ( $\tau \equiv 0$ ).
- Much more complicate:  $\exists$  global weak solution? (known for  $k = 0$ )

[Guillopé-Saut, 1990; PL Lions-Masmoudi, 2000; EFC et al., 2002; ...]

Linearized viscoelastic Jeffreys fluids (Stokes + memory)

$$\left\{ \begin{array}{ll} u_t - \nu \Delta u + \nabla p = \nabla \cdot \tau + \nu \mathbf{1}_\omega, & \nabla \cdot u = 0 \quad \text{in } Q, \\ \partial \tau + a \tau = 2b Du & \text{in } Q, \\ u = 0 & \text{on } \Sigma, \\ u(0) = u_0, \quad \tau(0) = \tau_0 & \text{in } \Omega, \end{array} \right.$$

where  $a, b > 0$ . Rewritten as an integro-differential equation:

$$(S) \quad \left\{ \begin{array}{ll} u_t - \nu \Delta u - b \int_0^t e^{-a(t-s)} \Delta u(s) ds + \nabla p = e^{-at} \nabla \cdot \tau_0 + \nu \mathbf{1}_\omega, & \text{in } Q, \\ \nabla \cdot u = 0 & \text{on } Q, \\ u = 0 & \text{on } \Sigma, \\ u(0) = u_0 & \text{in } \Omega. \end{array} \right.$$

## Theorem (Dobova, Fernández-Cara, 2012)

$\forall \omega \subset \Omega$ ,  $(S)$  is *Approximately-FD* at any time  $T > 0$ .

- Same result for **boundary controls**  $v|_{\gamma}$  on  $\gamma \times (0, T) \subset \Sigma$ .
- Equivalent to **unique continuation** property for adjoint problem.



When  $\nu = 0$  (only elasticity) in (S) we have a *linear Maxwell fluids*.

## Theorem (Boldrini, et al 2012)

Let  $\nu = 0$ . For suitable large  $\omega$ , (S) is exact controllable for large time.

- When  $b = 0$  (only viscosity) then (S) is the well-known *Stokes system*, that is NC.

Simplified case: Heat instead of Stokes

$$(H) \quad \begin{cases} \partial_t y - \Delta y - b \int_0^t e^{-a(t-s)} \Delta y(s) ds = 0 & \text{in } Q, \\ y = v \mathbf{1}_\gamma & \text{on } \Sigma, \\ y(0) = y_0, \quad \tau(0) = 0 & \text{on } \Omega. \end{cases}$$

## Theorem (Guerrero, Imanuvilov, 2013)

Let  $T > 0$  and  $\gamma \subset \partial\Omega$ .  $\exists u_0 \in L^2(\Omega)$  such that  $u(T) \not\equiv 0, \forall v$ .

- Same result for **distributed controls**  $v \mathbf{1}_\omega$ , where  $\bar{\omega} \subset \Omega$ .

## Question: Null controllability

Let us take  $\tau_0 = 0$  in (S). Is there a control  $v$  such that  $u(T) = 0$ ?

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The null controllability of system (S) **does not hold** for  $n = 2, 3$ . Consider the similar boundary controlled problem

$$\left\{ \begin{array}{ll} u_t - \Delta u - b \int_0^t e^{-a(t-s)} \Delta u(s) ds + \nabla p = 0 & \text{in } Q, \\ \nabla \cdot u = 0 & \text{on } Q, \\ u = v & \text{on } \Sigma, \\ u(0) = u_0 & \text{on } \Omega. \end{array} \right.$$

**Theorem (Fernández-Cara, Machado, Souza, 2020)**

$\exists u_0 \in H$  such that  $\forall v \in L^2(\Sigma)^n$  the solution  $u$  to above system satisfies

$$u(T) \neq 0.$$

# Non null controllability of the Stokes system with memory

**Sketch of the proof:** (Inspired by [Guerrero-Imanuvilov, 2013])

- Take  $\Omega$  as a ball  $\Omega = B(0; R)$ . **Not restrictive**
- NC is equivalent to **observability**

$$\|\varphi(\cdot, 0)\|^2 \leq C \iint_{\Sigma} \left| \left( -q \text{Id} + \nabla \varphi + b \int_t^T e^{-a(s-t)} \nabla \varphi(\cdot, s) ds \right) \cdot \nu \right|^2 d\Gamma dt, \quad \forall \varphi_T \in H$$

where  $\varphi$  is solution to

$$\begin{cases} -\varphi_t - \Delta \varphi - b \int_t^T e^{-a(s-t)} \Delta \varphi(\cdot, s) ds + \nabla q = 0 & \text{in } Q, \\ \nabla \cdot \varphi = 0 & \text{in } Q, \\ \varphi = 0 & \text{on } \Sigma, \\ \varphi(\cdot, T) = \varphi_T & \text{in } \Omega. \end{cases}$$

# Non null controllability of the Stokes system with memory

Idea of the demonstration

- $n=3$ ;
- $(\varphi_k, q_k)$ : eigenfunctions;  $\lambda_k$ : eigenvalues of the Stokes operator with

$$\left\{ \begin{array}{l} \varphi_k(x, y, z) = \frac{1}{\lambda_k^{1/2} R^2} \left( \cos(\lambda_k^{1/2} r) - \frac{1}{\lambda_k^{1/2} r} \sin(\lambda_k^{1/2} r) \right) (y - z, z - x, x - y), \\ q_k \equiv 0, \\ \lambda_k = \frac{\pi^2}{R^2} (k + 1/2)^2 - \varepsilon_k, \quad \text{for some } \varepsilon_k > 0 \text{ satisfying } \varepsilon_k \rightarrow 0. \end{array} \right.$$

- Estimates for  $\varphi_k$ :

$$\|\varphi_k\|^2 \geq \frac{2\pi R}{\lambda_k},$$

$$\frac{\partial \varphi_k}{\partial \nu} \Big|_{\partial \Omega} = -\frac{\sin(\lambda_k^{1/2} R)}{R^2} (y - z, z - x, x - y).$$

# Non null controllability of the Stokes system with memory

Idea of the demonstration

- Set  $\varphi_T := \sum_{k \geq 1} \beta_k \varphi_k$

- Then:  $\varphi(\cdot, t) = \sum_{k \geq 1} \alpha_k(t) \varphi_k, \quad q \equiv 0, \quad \forall t \in (0, T),$

$$\begin{cases} \alpha_k(t) \equiv 0 & \forall k < k_0, \\ \alpha_k(t) \equiv C_{1,k} e^{\mu_k^+(T-t)} + C_{2,k} e^{\mu_k^-(T-t)} & \forall k \geq k_0, \end{cases}$$

where  $\mu_k^+ \rightarrow -\infty$  and  $\mu_k^- \rightarrow -(a+b)$ .

- $\beta_k = 0$ , for  $k \neq 8M + \ell$  with  $1 \leq \ell \leq 8$



# Non null controllability of the Stokes system with memory

Idea of the demonstration: estimate

GOAL: to construct, for  $M$  large, a sequence of solutions  $\{\varphi^M\}$  such that:

$$(\star) \quad \frac{C_0}{M^6} \leq \|\varphi^M(0)\|^2 \quad \text{and} \quad \iint_{\Sigma} \left| \frac{\partial \varphi^M}{\partial \nu} \right|^2 d\sigma dt \leq \frac{C_1}{M^{10}},$$

for some  $C_0, C_1 > 0$  independent of  $M$ .

- Large  $M \implies$  Observability cannot hold.

# Non null controllability of the Stokes system with memory

Idea of the demonstration: estimate

The estimates from above

$$\iint_{\Sigma} e^{2(a+b)(T-t)} \left| \frac{\partial \varphi^M}{\partial \nu} \right|^2 d\Gamma dt \leq A_1 + A_2$$

## Lemma

There exists  $C > 0$  such that, for  $M$  large enough, one has

$$A_1 := 96\pi R^2 \int_0^T \left( \sum_M \gamma_k C_{1,k} e^{(a+b+\mu_k^+)(T-t)} \right)^2 dt \leq \frac{C}{M^{10}},$$

Integrating by parts ten times

$$A_1 = \sum_{j=0}^9 E_{1,j,M} g_M^{(j)}(0) - E_{2,j,M} g_M^{(j)}(T) + \int_0^T E_M(t) g_M^{(10)}(t) dt.$$

$$g_M^{(0)}(T) = g_M^{(1)}(T) = \dots = g_M^{(8)}(T) = g_M^{(9)}(T) = 0.$$

Homogeneous system, with 5 linear equations and 8 unknowns  $C_{1,8M+\ell}$  (or  $\beta_k$ ).

# Non null controllability of the Stokes system with memory

Idea of the demonstration: estimate

## Lemma

There exists  $C > 0$  such that, for  $M$  large enough, one has

$$A_2 := 96\pi R^2 \int_0^T \left( \sum_M \gamma_k C_{2,k} e^{(a+b+\mu_k^-)(T-t)} \right)^2 dt \leq \frac{C}{M^{12}},$$

Expanding

$$\gamma_k C_{2,k} e^{(a+b+\mu_k^-)(T-t)} = \beta_k \left[ E_{1,k} + E_{2,k}(T-t) + \mathcal{O}(\lambda_k^{-3}) \right]$$

$$\sum_M \beta_k E_{1,k} = 0 \quad \text{and} \quad \sum_M \beta_k E_{2,k} = 0$$

Homogeneous system, with 7 linear equations and 8 unknowns  $\beta_k$ .

It is possible to choose a nontrivial solution bounded independently of  $M$ .

# Non null controllability of the Stokes system with memory

Idea of the demonstration: estimate

The estimates from below

## Lemma

There exists  $C > 0$  such that, for  $M$  large enough, one has

$$\|\varphi^M(0)\|^2 \geq \frac{C}{M^6}$$

$$\|\varphi(\cdot, 0)\|^2 = \sum_{k \geq k_0} (C_{1,k} e^{\mu_k^+ T} + C_{2,k} e^{\mu_k^- T})^2 \|\varphi_k\|^2 \geq C \sum_M \frac{1}{\lambda_k} \left( \frac{3}{4} C_{2,k}^2 e^{2\mu_k^- T} - 3 C_{1,k}^2 e^{2\mu_k^+ T} \right).$$

- $C_{2,k} \approx \mathcal{O}(\lambda_k^{-1})$
- $\mu_k^- \rightarrow -(a+b)$
- $C_{1,8M+\ell}^2 e^{2\mu_{8M+\ell}^+ T} \leq C e^{-CM^2 T} \quad \forall \ell = 1, \dots, 8$

# Non null controllability of the Stokes system with memory

Idea of the demonstration: construction of the initial condition

## Construction of the initial condition

We define

$$u_0 = \sum_{j \geq 1} \frac{1}{j^{3/4}} \frac{\varphi_{8j+\ell_0}}{\|\varphi_{8j+\ell_0}\|}.$$

By contradiction, let  $v \in L^2(\Sigma)$  be such that  $u(T, \cdot) = 0$ .

$$\underbrace{- \int_{\Omega} u_0 \varphi^M(0)}_{X_1} + \underbrace{\int \int_{\Sigma} v \frac{\partial \varphi^M}{\partial \nu} + b \int_0^T \int_0^t e^{-a(t-s)} \left( \int_{\partial \Omega} v(s) \frac{\partial \varphi^M}{\partial \nu}(t) \right) ds dt}_{X_2} = 0$$

From (★)

$$|X_1| \geq \frac{C_0}{M^{15/4}} \quad \text{and} \quad |X_2| \leq \frac{C}{M^5}.$$

Taking  $M$  large enough we have a contradiction.

## Corollary

Same result for distributed controls  $\chi_{\omega}$ , where  $\omega \subset \Omega$  is a non-empty open set with  $\Omega \setminus \bar{\omega} \neq \emptyset$ :

NC is true  $\forall \omega$  and  $\forall u_0 \implies$  Contradiction

## Remark

Theorem and Corollary still hold if we replace the integral (memory) term by

$$\int_0^t e^{-a(t-s)} u(\cdot, s) ds$$

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- For two-dimensional ( $n = 2$ ) case the proof is similar.

$$\varphi_k(x, y) = \frac{J_1(\lambda_k^{1/2} r)}{\lambda_k^{1/2} r} (-y, x) \quad q_k \equiv 0 \quad \lambda_k^{1/2} R = j_{1,k},$$

where  $J_1$  is the first order Bessel function of the first kind and  $j_{1,k}$  its  $k$ -th positive root.

- Using  $n - 1$  controls, AC in  $u$  is **true**.  
 $n = 3$ , using only one control? In general, **NO!**  $\Omega = B(0; R) \times (0, L)$ .
- Oseen equation with memory?

$$\begin{cases} u_t + (z \cdot \nabla)u - \Delta u - b \int_0^t e^{-a(t-s)} \Delta u(s) ds + \nabla p = 0 \\ \nabla \cdot u = 0 \\ \text{etc.} \end{cases}$$

- Is it possible to use **moving controls** for Stokes with memory?  
In [Chaves-Silva, Rosier, Zuazua, 2014] NC of a simplified similar system, with  $\omega = \omega(t)$ .



## References



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Thank you very much!